

## Asteroid Capture Robotics

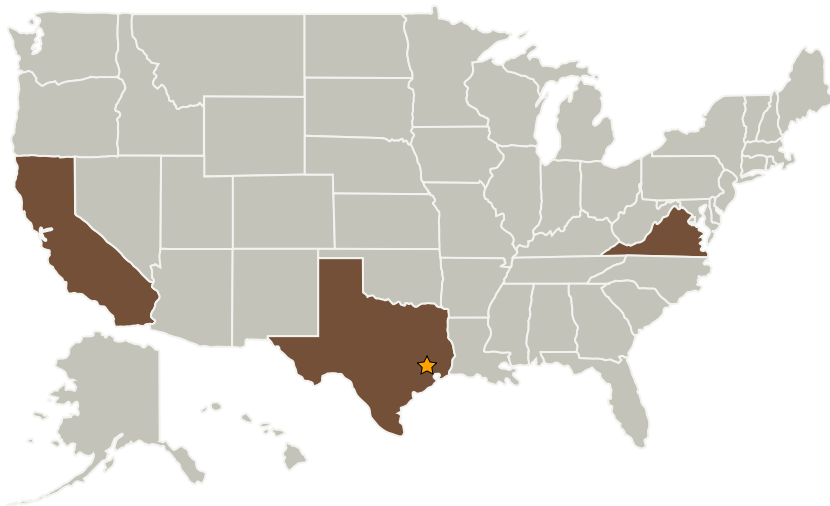
Completed Technology Project (2014 - 2015)



## Project Introduction

TALISMAN greatly improves the state-of-the-art in space robotics by significantly increasing manipulator reach and dexterity while reducing mass and complexity. It provides new capabilities that can be used for asteroid retrieval missions and other activities, such as astronaut positioning, payload retrieval, in-space assembly and satellite servicing.

## Primary U.S. Work Locations and Key Partners



Organizations Performing Work	Role	Type	Location
★ Johnson Space Center(JSC)	Lead Organization	NASA Center	Houston, Texas

Primary U.S. Work Locations	
California	Texas
Virginia	

## Project Transitions

▶ **October 2014:** Project Start



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## Organizational Responsibility

**Responsible Mission Directorate:**

Space Technology Mission Directorate (STMD)

**Lead Center / Facility:**

Johnson Space Center (JSC)

**Responsible Program:**

Game Changing Development

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✓ **September 2015:** Closed out

### Stories

2015-07-30 JPL Hedgehog  
(<https://techport.nasa.gov/file/164917>)

### Project Website:

<https://www.nasa.gov/directorates/spacetech/home/index.html>

### Project Management

#### Program Director:

Mary J Werkheiser

#### Program Manager:

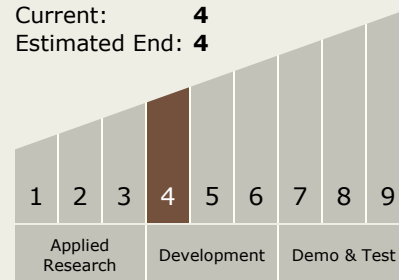
Gary F Meyering

#### Principal Investigator:

William J Bluethmann

### Technology Maturity (TRL)

Start: 4  
Current: 4  
Estimated End: 4



### Target Destinations

The Moon, Mars, Others Inside the Solar System